

Program Analysis

Call Graphs (Part 4)

Prof. Dr. Michael Pradel

Software Lab, University of Stuttgart

Winter 2020/2021

Overview

- Introduction
- Single & efficient: CHA, RTA
- Analyzing assignments: VTA, DTA
- Call graphs and points-to analysis:
Spark



Spark: Idea

- RTA, DTA, and VTA: Instances of one **single unifying framework**
- General recipe
 - First, built **pointer-assignment graph** (PAG)
 - **Propagate information** through graph
- **Combine call graph construction with points-to analysis**
 - Reason about objects a variable may refer to

Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation
- Variable
- Field reference

■ Edges

- Allocation
- Assignment
- Field store
- Field load

Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation →
- Variable
- Field reference

- One for each **new A()**
- Represents a **set of objects**
- Has an **associated type**, e.g., **A**


■ Edges

- Allocation
- Assignment
- Field store
- Field load

alloc₁

Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation
- Variable 
- Field reference

■ Edges

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- One for each **local variable, parameter, static field, and thrown exception**

- Represents a memory location holding **pointers to objects**

- May be typed (depends on setting)



Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation
- Variable
- Field reference →

■ Edges

- Allocation
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- Field load

■ One for each $p.f$

■ Represents a **pointer
deference**

■ Has a variable node as
its base, e.g., p

■ Also models contents
of arrays:
 $a.<elements>$


$p.f$

Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation
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■ Edges

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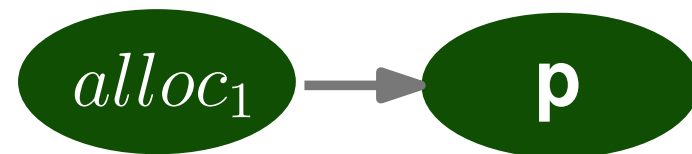
- Represents **allocation** of an object **assigned** to a **variable**

- E.g., for

```
p = new HashMap();
```

or

```
s = "foo";
```

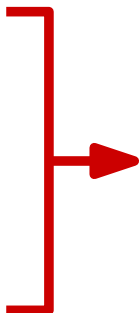


Pointer-Assignment Graph (PAG)

■ Nodes

- Allocation
- Variable
- Field reference

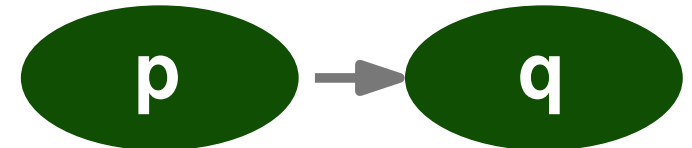
■ Edges

- Allocation
 - Assignment
 - Field store
 - Field load
- 

- Represent **assignments among variables and fields**

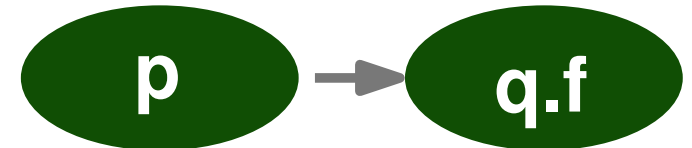
- E.g., for

$q = p;$



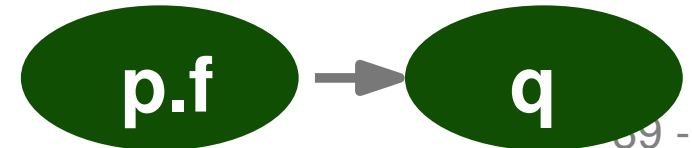
or

$q.f = p;$



or

$q = p.f;$



Example

```
static void foo() {  
    p = new A(); // alloc1  
    q = p;  
    r = new B(); // alloc2  
    p.f = r;  
    t = bar(q);  
    t.m();  
}
```

```
static C bar(C s) {  
    return s.f;  
}
```

alloc₁



p



q



s

alloc₂



r



p.f

.

s.f



t

Points-to Sets

- For each variable, **set of objects the variable may refer to**

- Objects represented as allocation nodes

- **Example:**

```
a = new X(); // alloc1
```

```
...
```

```
a = new Y(); // alloc2
```

$$pts(a) = \{alloc_1, alloc_2\}$$

Subset-based Analysis

- **Allocation and assignment edges induce subset constraints**

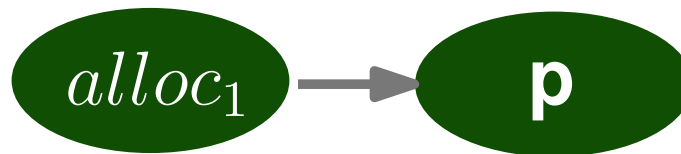
- Reason: Just because we know that

- `p = new 1;`

- does not mean that later we cannot see

- `p = new 2;`

- **Example:**



induces constraint

$$\{alloc_1\} \subseteq pts(p)$$

Subset-based Analysis

- **Allocation and assignment edges induce subset constraints**

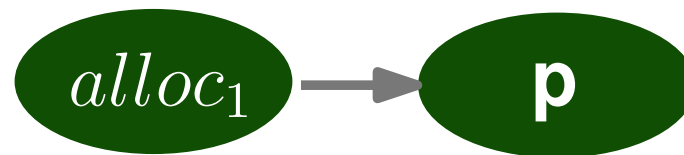
- Reason: Just because we know that

- `p = new 1;`

- does not mean that later we cannot see

- `p = new 2;`

- **Example:**



induces constraint

$$\{alloc_1\} \subseteq pts(p)$$

Note: Analysis is flow-insensitive, i.e., values are never assumed to be overwritten

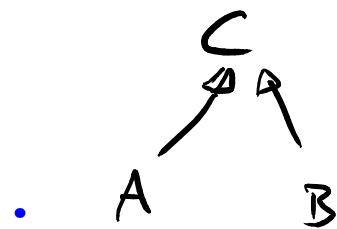
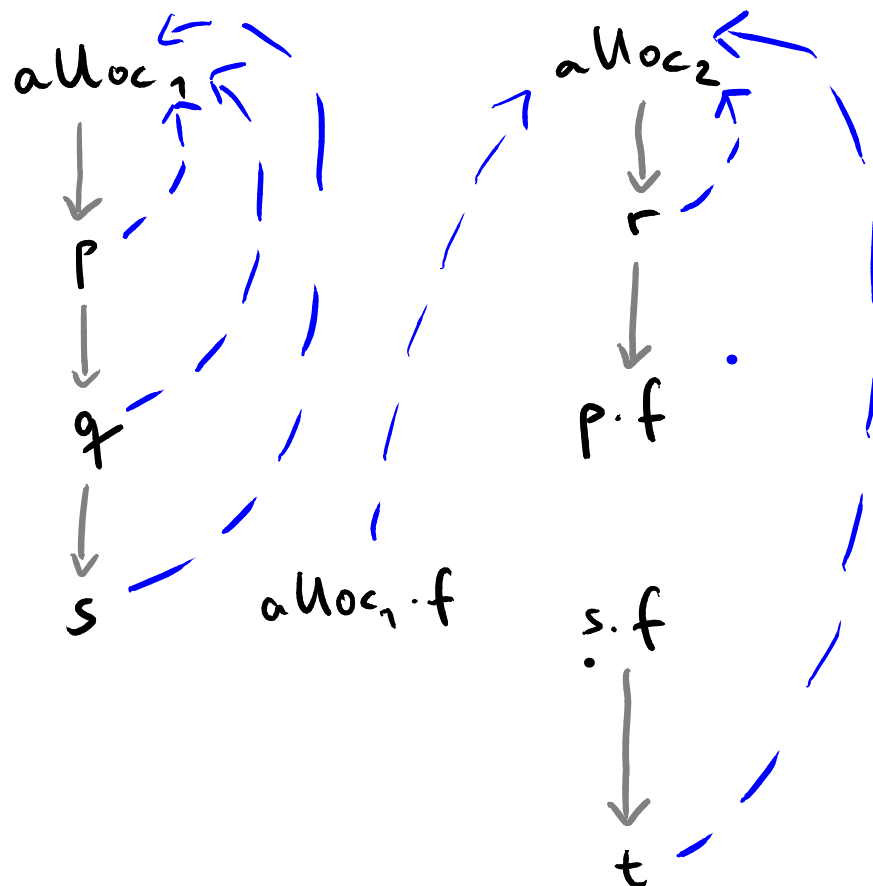
Computing Points-to Sets

- New helper node: **Concrete fields**
- Represents all **objects pointed to by field ϵ** of all objects created at **allocation site**
 - E.g., *alloc₁.f*

Computing Points-to Sets (2)

Iterative propagation algorithm

- **Initialize** $pts(v)$ according to **allocation edges**
- Repeat until no changes
 - **Propagate** sets along **assignment edges** $a \rightarrow b$
 - For each **load edge** $a.f \rightarrow b$:
 - For each $c \in pts(a)$, **propagate** $pts(c.f)$ to $pts(b)$
 - For each **store edge** $a \rightarrow b.f$:
 - For each $c \in pts(b)$, **propagate** $pts(a)$ to $pts(c.f)$



• Call goes to $B.m()$

---> points-to

Simpler Variants

- **Spark framework supports many variants**
 - Just one allocation site per type
 - Fields simply represented by their signature
 - Equality instead of subsets for assignments
 - Etc.

Spark

■ Pros

- **Generic algorithm** where precision and efficiency can be tuned
- Jointly computing **call graph and points-to sets** increases precision

■ Cons

- Still **flow-insensitive**
- Can be quite **expensive** to compute